Spatial and Spectral Features Utilization on a HyperSpectral Imaging System for Rice Seed Varietal Purity Inspection

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Abstract—A conventional method to inspect the varietal purity of rice seeds is based on evaluating human visual inspection where a random sample is drawn from a batch. This is a tedious, laborious, time consuming and extremely inefficient task. This paper presents an automatic rice seed inspection method using Hyperspectral imaging and machine learning, to automatically detect unwanted seeds from other varieties which may be contained in a batch. Hyperspectral image data from Near-infrared (NIR) and Visible cameras are acquired for six common rice seed varieties. The results of applying two classifiers are presented, a Support Vector Machine (SVM) and a Random Forest (RF), where each consists of six one-versus-rest binary classifiers. The results show that combining spectral and shape-based features derived from the rice seeds, increase precision of the multi-label classification to 84% compared 74% when only visual features are used.

I. INTRODUCTION

Ensuring rice seed quality is a significant challenge for the large rice export nations such as India, Thailand, US and Vietnam. Rice seed impurities can impact on the yield by introducing weeds and off-types into the crop making it susceptible to disease. The consequences are not limited to a decrease in yield but also to the grade and price of the produce. A responsibility lies with rice seed producers to ensure high quality seed and a critical procedure is the batch screening and inspection. Conventional methods to inspect seeds, as shown in Fig.1(a), rely on extracting a sample from a batch and human visual inspection. The inspection of the sample is performed visually to assess the grain properties, such as shape, length, width and size. This task is tedious, laborious, time consuming and requires trained and experienced personnel.

Recently, the cost and size of Hyperspectral Imaging (HSI) Systems has reduced significantly. This technology has emerged as a useful tool in food sciences and applications. Such systems provide spatial and textural information like other traditional cameras with the added advantage that they offer high resolution spectral signatures for each pixel in the image data acquired. In this paper, we investigate the benefits of analyzing the extracted features taken from a HSI system to solve issues of rice seed varietal purity inspection. We deploy an automatic inspection method which combines hyperspectral imaging and tools from machine learning to automatically detect seeds which are erroneously contained within a batch when they actually belong to a completely different species. In this study, the purity of six common rice seed varieties, as shown in Fig.1(b), are examined.

Automatic rice seed inspection systems that employ machine vision addressing this challenge have been shown in previous works [1]–[3]. Commonly, shape descriptors of the seed samples are extracted through image processing and vision-based approaches [1], [3], [4]. The challenge in comparing and quantifying performance between these approaches, is that each one has been evaluated on different rice seed varieties. It is therefore unclear if the differences in performance come from better feature descriptors or if this is due to varying inter-class/intra-class among the examined species. In this study, a HSI system provides both spatial and spectral information about the seed samples. Therefore, the inspection techniques that utilize both types of feature should be investigated. We formulate the purity inspection problem as six one-versus-rest binary classifiers. In this work, the binary classifiers are built using a SVM and a RF, and both approaches are compared. While the spatial features measure physical properties of rice seed, the mean spectrum of all pixels in a seed sample can be used to infer chemical properties of the species. Thanks to discriminant analysis techniques, the combinations of both features show significant benefits and potential in hyperspectral imaging, particularly, to develop a machine vision system for rice seed quality assessments.

The remainder of paper is organized as follows. Section II briefly describes related techniques for rice and rice seed
quality assessments using vision-based/HSI systems. Section III describes the device setup, data acquisitions and correction procedures. Section IV presents the feature extraction approach. Section V analyzes inter-and intra-class variations of the examined species. Section VI reports the classification results. Finally, Section VII concludes the work and suggests further research directions.

II. RELATED WORK

There are many machine vision systems for food quality evaluation. A good survey can be found in Da-Wen Sun’s textbook [5]. In Chapter 16 of this textbook, Y. Ogawa comprehensively surveys rice grain quality evaluation techniques using computer vision technology which analyzes features such as physical property measurements and compound content and distribution. Deploying such vision-based systems has been widely investigated. Lai et al. [6] applied an interactive image analysis method for determining the physical dimensions and classifying the variety of grains. In [7], the authors measured physical dimensions such as grain contour, size, color variance and distribution, and damage. Sakai et al. [8] demonstrated the use of two-dimensional image analysis for the determination of the shape of brown and polished rice grains of four varieties. Z.Lui et al. [1] implemented a method of identification based on neural networks to classify rice variety using color and shape features. Guzman et al. [9] investigated grain features extracted from each sample image. They then utilized multilayer artificial neural network models for automatic identification of 52 rice grains. More recent works [1]–[3] focused on rice seed variety classification. Commonly, shape descriptors of the seed samples are extracted, then the classifiers such as Random Forests [3], Neural Networks [1] or Cubic B-Splines shape model [4] are trained. An automatic machine-vision system includes several stages, in which the most important steps are image data collection, feature extraction (such as shape, size, color, and orientation etc.), and feature representations via models using pattern recognition algorithms or multivariate analysis techniques.

Recently, HSI systems have been widely used in food and agriculture engineering. The authors in [10] give a broad range of HSI applications for beef, pork, fruits, and plant products quality evaluations. For the rice grain quality inspection, [11] used a range of VIS/NIR spectral (400-1000 nm) information for discriminating three rice varieties. By using Principle Component Analysis (PCA) and Back Propagation Neural Network (BPNN), they achieved a classification accuracy of 89.18 and 89.91 % for PCA and BPNN model, respectively. The authors in [12] find out that a combination of the Least squares support vector machine (LS-SVM) regression method and Vis/NIR spectroscopy at range 325-1075 nm provides a realizable technique to monitor the nitrogen status in rice. More recently, a HSI system has been used in [13] for identifying four rice seed cultivars. By utilizing the full spectral range 1,039-1,612 nm, they achieved very promising results, that is up to 100% accuracy with a Random Forest (RF) classifier. However, four cultivars in [13] were hybridized from other species, therefore, it is unclear how the inter/intra class varies among them. In this paper, we extract and combine both spatial and spectral features from the hyperspectral datacube acquired by a HSI system with range of NIR spectral. We argue that the combination of features increases classification performance.

III. RICE SEED SAMPLE DATA COLLECTIONS USING A HYPER SPECTRAL IMAGING SYSTEM

A. Hyperspectral Imaging System Setup

The experimental setup of the data acquisition system is shown in Fig.2(a). The NIR HSI system used to capture the data was the Inno-Spec™ Redeye 1.7 model (Inno-Spec GmbH, Germany) capturing 256 wavelengths from 950.73 - 1759.4 nm. The HSI device operates using a line scan where the spectral info from an entire row of pixels is captured at any given time. For this purpose, a conveyor platform (the stage) was positioned underneath the imager to allow HSI scanning. Two halogen bulbs were used to illuminate the scene and the bulbs were positioned to create balanced illumination across the scan line. To ensure repeatable data acquisitions, the halogen bulbs were switched on and allowed to reach stable operating temperature before the data were acquired in a dark room to minimise illumination variability between captures. To properly collect the data, three parameters in the HSI system needed to be adjusted:

- The exposure time of the camera (e.g., 500 ms) versus the speed of movement of the stage (5 mm/s), which should be calibrated in order to avoid spatial distortions;
- A trade-off between the exposure time and the aperture of camera (f=1/8) to ensure a suitable light intensity;
- The height between the lens and the stage which is adjusted so that whole seed samples area are in field-of-view of the camera. A photo of the real HSI system is shown in Fig. 2(b).

B. Rice seed dataset acquisition

Six rice seed varieties (as shown in Fig.1(b)) were obtained from a seed production company in Vietnam: BC15, BT07, Khang dan 18 (shortly named KD18), N97, Nep Lang Lieu (LL), and Q5. The selected varieties are the most frequently planted in North Vietnam. The producer screened the samples using experienced technical staff to ensure that each sample
The sample population of each variety consisted of 108 seeds with 648 seeds across all varieties. The 108 samples from each species was then divided to 3 batches with 36 samples each. The 36 seeds were positioned on a white sheet of paper constructing a $6 \times 6$ matrix (e.g., as shown in Fig.3(a)-(c)), that was placed on a conveyor platform for imaging by the NIR camera. This resulted in 3 hyperspectral datacubes per variety resulting in 36 total number of the datacubes.

C. Data correction

Let $y$ denote a datacube consisting of reflectance values $\lambda$ as a two-parameter set:

$$y_{\lambda}(x), x \in X, \lambda \in \Lambda$$  \hspace{1cm} (1)

where $\lambda$ represents a wavelength belonging to $\Lambda$, that is a set of the wavelengths at NIR (Near-Infrared) range 950.73-1759.4 nm and $x$ represents a pixel in $X$ where $X$ is 2-D coordinate by row $m$ and column $n$. For each specific wavelength, the array of reflectance values can be regarded as an image where spatial relationships between the pixel reflectance values have meanings. For example, Fig. 3 represents three images acquired by the device at specific wavelengths of 1109.3 nm, 1267.78 nm, and 1424.61 nm. It is noticed that at each $x$, the raw reflectance value could vary due to different lighting conditions. To reduce the variation in the acquired reflectance values among acquisition data and scale the data relative to known max reflectance value, we normalize the raw data as below:

$$y_{\lambda}(x) := \frac{y_{raw,\lambda}(x) - b(n, \lambda)}{w(n, \lambda) - b(\lambda, \lambda)}, \lambda \in \Lambda$$  \hspace{1cm} (2)

where $b(n, \lambda)$ and $w(n, \lambda)$ are the reflectance values of reference dark and white objects. The dark object is setup by covering the lens-cap and the white object is a white spectralon tile which is a highly reflective Lambertian scatter commonly used to calibrate HSI systems. For each $\lambda$, $b(n)$ and $w(n)$ are averaged on reflectance values at column $n$ along the white tile’s height dimension. The images shown in Fig.3(a)-(c) have been normalized. Corresponding wavelength profiles of the rice seeds are shown in Fig. 3(b).

IV. SPATIAL AND SPECTRAL FEATURE EXTRACTIONS

A. Separating seed samples from background

In the proposed system, rice seed samples need to be separated from background regions in order to allow the extraction of the physical properties of the grain as well as spectral features. However, seed segmentation is not a straightforward procedure because of artefacts such as shadow and lighting conditions. This task also suffered due low spatial resolution of the hypercubes data. Thus, we deploy a series of image processing techniques to overcome these difficulties. Firstly, we consider the difference of low-band and high-band images, as shown in Fig.3(a) and Fig.3(c), respectively, to boost contrast. This difference image $I_{diff}$ differentiates between background regions and foreground ones (e.g., rice seed regions). A morphological opening operator is then applied on the difference image, named background image $I_{bg}$. As inherited from a Top-hat transform, the foreground image $I_{fg} = |I_{diff} - I_{bg}|$ making by subtraction $I_{diff}$ and $I_{bg}$. An example of $I_{fg}$ is shown in Fig. 4(a). Comparing with original image at a specific wavelength (e.g., Fig. 3(a)-(c), the shadow and artifacts in $I_{fg}$ are eliminated. Consequently, a thresholding operator using Otsu’s threshold is applied on $I_{fg}$. The extracted seeds are marked by the red boundary in Fig.4(b).

B. Spatial Feature extractions

Given an individual rice seed from batch samples, we measures spatial/morphological features. These features are se-
collected because of their effectiveness for discriminating among species, as shown in recent works such as [3] and [1]. A morphological feature descriptor $f$ with 6 dimensions is calculated as follows:

- $f_1$: is the number of pixels inside a seed sample
- $f_2, f_3$: are MajorAxisLength and MinorAxisLength that specify the length (in pixels) of the major/minor axis of the ellipse that covers the boundary of the sample seeds.
- $f_4 = \frac{\text{MinorAxisLength}}{\text{MajorAxisLength}}$ and $f_5 = \frac{\text{Perimeter}}{\text{MajorAxisLength}}$, where Perimeter is number of pixels along the seed boundary; and Area is $f_1$ feature.
- $f_6 = \frac{\text{FociDistance}}{\text{MajorAxisLength}}$ is eccentricity specified by FociDistance which is the distance between two foci of the ellipse, and the major axis length.

These features are illustrated in Fig. 5(a). Note that different from [3], the HSI camera gives a low resolution spatial image of each seed (e.g., 40 x 50 pixels) versus seed samples collected from high resolution CCD camera [3] (e.g., 630 x 900 pixels, as shown in Fig. 5(b)-(c)). This difference degrades the discrimination ability between the rice species when using only spatial features.

C. Spectral feature extractions

A hyperspectral datacube consists of spectral information from every pixel of the seed regions. The mean spectrum of all pixels in such regions is used as spectral features. In this paper, for each seed, spectral profiles of one rice seed species are shown in Fig. 3(d). As denoted in (2), a raw spectral feature vector of a rice seed sample is a set of $y_\lambda$ in which $\lambda$ is one of 256 bands belonging a range $\Lambda = 950.73 - 1759.4nm$. Fig 7(a)-(b) shows the spectral features of two seed samples. The mean spectrum over seed regions are shown in the corresponding profiles in right panels.

Dimensionally reduction is widely applied in spectral data analysis due to the redundancy and co-linearity of spectral data. This also facilitates the construction of simple, stable and practical classification models. To do so, Principal Component Analysis (PCA) has been widely used with large datasets like the collected datacube. PCA helps to transform the original data into a small number of uncorrelated variables. A PCA transformation is applied on the spectrum profile of the whole collected data:

$$\begin{bmatrix}
  s_1 \\
  s_2 \\
  \vdots \\
  s_{648}
\end{bmatrix}
= \begin{bmatrix}
  f_{\lambda_1} & f_{\lambda_2} & \cdots & f_{\lambda_{256}} \\
  f_{\lambda_1} & f_{\lambda_2} & \cdots & f_{\lambda_{256}} \\
  \vdots & \vdots & \ddots & \vdots \\
  f_{\lambda_1} & f_{\lambda_2} & \cdots & f_{\lambda_{256}}
\end{bmatrix}
$$

Results of PCA provide a mean $\mu_\Theta$ and eigenvectors $\nu_\Theta$. Given the normalized datacube $y_\lambda$, the projected data in a PCA space is defined by:

$$y_\lambda \rightarrow \sum_{j=1}^{pc_{10}}f_{\lambda j} \cdot \nu_\Theta^T(c_\lambda - \mu_\Theta) \quad (3)$$

The first few principal components (PCs) can be used to explain most of the sample data, which results in the data dimension reduction. In our dataset, the first ten PCs ($f_{pc1}, \ldots, f_{pc10}$) can reconstruct 99% original data. The consistence of the reconstructed data using first ten PCs versus all of the original data is illustrated in Fig. 6. Therefore, the first ten PCA-based features rather than entire spectral data are utilized as spectral features for each seed sample to build and apply classification models.

V. DISCRIMINANT ANALYSIS AND CLASSIFICATION

A. Species discrimination using spectral features

Many relevant works [1]–[3] have evaluated shape-based properties for identifying/separating rice seed species. However, these measurements strongly depend on the grain’s positioning on the captured surface. For example, Fig. 7(a)-right panel shows an illustration of two seeds of the same species. The shape-based properties of these seeds such as perimeter, MinorlengthAxis should not be same in this case. Conversely, the spatial appearance of two different species may be very similar, e.g. two seeds shown in Fig. 7(b)-right panel. The benefit of the HSI system is that it can measure hidden information inside the seeds. As expected, the wavelength profiles of two seeds in Fig. 7(a) are very similar. In the same way, the wavelength profiles of the seed samples from two different species in Fig. 7(b) are separable. Statistically speaking, the wavelength profiles of each species is averaged based on a hyperspectral datacube collected from 108 seed samples. Pair comparisons between one species with others are shown in Fig. 8(a)-(e).
profiles; Right panel: Averaged wavelength profiles. Photos of the rice seed samples for references

...is based on the structural risk minimum (SRM) and SVM has advantages in dealing with small sample, non-linear and high dimensional data. SVM shows advantages in dealing with a large amount of data. RF is a fast and effective algorithm for dealing with a large amount of data. RF has shown the advantages that it reduces variance and achieves comparable classification accuracy. In this study, number of the decision trees is equal 500.

Support Vector Machine is a widely used supervised statistical learning algorithm. SVM shows advantages in dealing with small sample, non-linear and high dimensional data. SVM is based on the structural risk minimum (SRM) and SVM has high generalization capacity and could provide a flexible and easy-to-compute solution. Selection of the kernel function in SVM models has a significant influence in model performance, and in this study, the commonly used Radial Bias Function (RBF) is employed as kernel function.

**B. Building Classifiers**

Utilizing the spatial, and spectral features, as well as their combination, we build classifiers that come from two different classification methods.

**Random Forest** is a machine learning algorithm combining a 'bagging' idea and a "random subspace method". A RF classifier contains many decision trees, and each tree is grown from a bootstrap sample of the response variable. The best split is selected from a random subset of variables at each node of the tree, and then the tree grows to the maximum extent without pruning. Prediction can be made from new data by aggregating the outputs of all trees. RF is a fast and effective algorithm for dealing with a large amount of data. RF has shown the advantages that it reduces variance and achieves comparable classification accuracy. In this study, number of the decision trees is equal 500.

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**VI. EXPERIMENTAL RESULTS**

We evaluate the performance of each set of features (spatial, spectral individually, and their combination) on the collected dataset, as described in Section III-B. The feature extraction procedures were implemented using Matlab on a PC Core i5 3.10GHz CPU, 4GB RAM. The LibSVM library [14] and a Random Forest Library [15] were adopted to build classifier models. To validate the proposed method, leave-p-out-cross-validation was utilized. For each classifier, 50 seed samples were collected randomly as positive samples, the negative samples were collected from all other species so that total negative samples are equal 50 (in other words, 10 from each other species). To evaluate the performance, two criteria measures are defined in (4). The performance criteria are calculated by averaging over 10 runs.

\[
\text{Precision}(P) = \frac{tp}{tp + fp}, \quad \text{Recall}(R) = \frac{tp}{tp + fn} \quad (4)
\]

where \(tp\) is the number of true positive, \(fp\) is the number of the false positive, \(tn\) is the number of true negative and \(fn\) is the number of false negative.

The performance of the classifiers using only the spatial features \((f = f_1, \ldots, f_6)\) is given in Table I. As shown, the RF classifier is slightly better than the SVM and the best performance is achieved with the LL species. Utilizing only the raw spectral data, Table II shows higher performances for \(BT07, KD18, LL, N97\) than that using only spatial features. By combining the spatial and the spectral features together, a feature vector consists of 256 + 6 dimensions. Results utilizing the combination of features are shown in Table III. Obviously, the performance increases from 77-78% precisions by using only spatial or spectral features to 81% when combined. Finally, by using 10 principal components (to reduce the dimensionality of the spectral data) and spatial features, overfitting issues are eliminated. This results in higher performance and the techniques achieved the precision at 84%. These evaluations confirm the benefits of the features extracted from a HSI system.
VII. CONCLUSION AND DISCUSSION

Conclusion: This paper describes a HSI system supporting rice seed varietal purity inspection. The proposed system combines a hardware camera setup and a tool for extracting features from the collected hyperspectral data cubes. We have confirmed that by taking advantage of a HSI system on both spatial and spectral features, we achieve very promising results on eliminating impurity species from large seed samples.

Discussion: Utilizing similar spatial features, [3] reported 90% precision on using a RF classifier. That results are higher than that shown in Table I. However, the imaging acquisition used in [3] is a high resolution camera. As shown in Fig 5(b), the shape properties of the segmented seeds therefore are described more precisely in [3] than the seed samples collected by our HSI system. This observation suggests a new imaging modality in the future. Going forward, we will combine data from registered high resolution images from a CCD camera with spectral images from HSI sensor to improve upon work of [3].

A map of the spatial distribution of the chemical constituents in a rice seed sample can be generated from spectral data. There are evidences given in [16] in which intuitive chemical components in wheat kernels is observable by a HSI system. Therefore, we believe that utilizing the spectral data at each pixel rather than mean spectrum on all of the pixels of the seed regions can be useful to investigate internal features of a seed. Consequently, visually discriminating two different species will be better.

ACKNOWLEDGEMENTS

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TABLE I

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TABLE III

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TABLE IV

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